

MULTIMEDIA



UNIVERSITY

STUDENT ID NO

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MULTIMEDIA UNIVERSITY

FINAL EXAMINATION

TRIMESTER 1, 2017/2018

EEE 3076 – POWER ELECTRONICS

(LE, EE, CE, NE)

16 OCTOBER 2017
9:00 AM – 11:00 AM
(2 Hours)

INSTRUCTIONS TO STUDENTS

1. This Question paper consists of 10 pages including cover page with 4 Questions only.
2. Answer ALL questions. All questions carry equal marks and the distributions of the marks for each question is given.
3. Please print all your answers in the Answer Booklet provided.

Question 1

- a) Using an aid of a BJT driver circuit and its current waveform, briefly explain how the gate/base driver circuit can improve switching speed for a switching power converter. [7 marks]
- b) A Power BJT (Motorola MJ16018 - Appendix A-1 and A-2) is used as a switch for a DC-DC converter connected to a resistive load. The input voltage is 250 V and maximum output current is 5 A. The switch is operated at 25 kHz with 50% duty cycle. Estimate the following for the case temperature of 25°C. (Note that, $\tau_{ON} = t_d + t_r$ and $\tau_{OFF} = t_s + t_f$)
- (i) Static Loss [6 marks]
 - (ii) Dynamic Loss [9 marks]
 - (iii) Total Loss [3 marks]

Continued...

Question 2

Design a full wave rectifier for a 20 kW resistive-inductive load. The application needs variable dc voltage to the load. You may need to select a suitable AC voltage for this application. Available AC voltage is 400V, 50Hz (for 3-phase system) and 230V, 50Hz (for 1-phase system).

- a) Sketch the rectifier circuit diagram. [4 marks]
- b) Compute the maximum average load voltage. [5 marks]
- c) Sketch the voltage waveform across one of the switches. (use drawing sheet in appendix) [6 marks]
- d) What should be the minimum current and breakdown voltage for the switch used in the rectifier? [4 marks]
- e) Prove by calculation that the rectifier can produce dc voltage ranging from 200 V to 400 V to the load. [6 marks]

Continued...

Question 3

- a) Figure 3 (a) is a buck converter circuit. Design this converter to power a load that consumes 28 W to operate. Assume that the buck converter will be operating in the continuous current mode and all the components are ideal. The load requires a voltage with ripple not more than 1%. Following are other requirements :

Input voltage, $V_d = 10$ V, duty cycle, $D = 0.5$ and switching period, $T_s = 40$ μ s.

[13 marks]

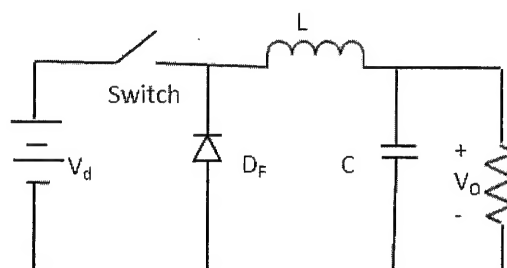


Figure 3 (a)

- b) Consider a buck-boost converter as shown in Figure 3 (b) that supplies 120 W at 10 A from a 40 V DC source. The converter operates at the switching frequency of 10 kHz and given the inductor in the circuit is 250 μ H. Determine the following:

- (i) The duty cycle D. [3 marks]
- (ii) The minimum and maximum inductor current (I_{Lmin} , I_{Lmax}). [4 marks]
- (iii) The average input current. [2 marks]
- (iv) The average diode current. [1 mark]
- (v) Sketch the waveforms of the output voltage and the inductor current. [2 marks]

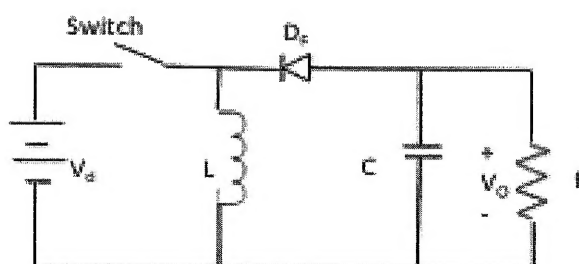


Figure 3 (b)

Continued...

Question 4

- a) A pulse width modulated full bridge inverter produces output AC voltage as shown in Figure Q4(a). The inverter is operating at a duty cycle of 55 % with a frequency of 50 Hz. The resistive load is $12\ \Omega$.

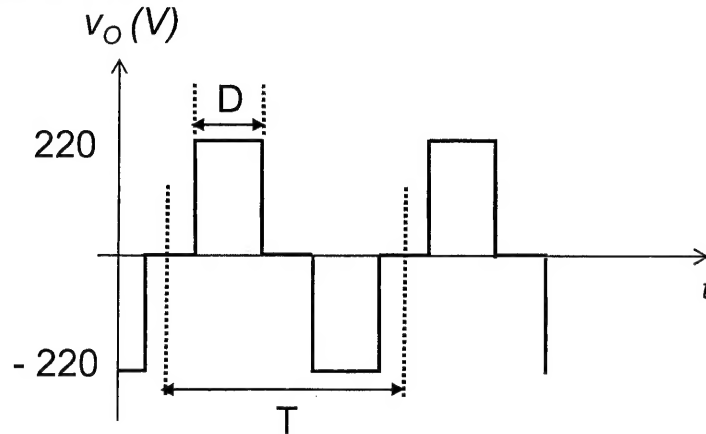


Figure Q4(a)

- Calculate the r. m. s. value of output load current (i_o) and output load voltage (v_o) for the first, third, and fifth harmonics. [7 marks]
 - Show by calculation that the inverter can eliminate the third current harmonics at the load. [4 marks]
 - Calculate the total harmonic distortion (THD) of the output current for part (i) and (ii) above. [8 marks]
- b) A resonant inverter shown in Figure Q4(b) has the following circuit parameters: Show by calculation that the inverter operates in non-overlapping mode.
 $R = 2\ \Omega$, $L = 30\ \mu\text{H}$, $C = 17\ \mu\text{F}$, Output frequency = 2 kHz,

[6 marks]

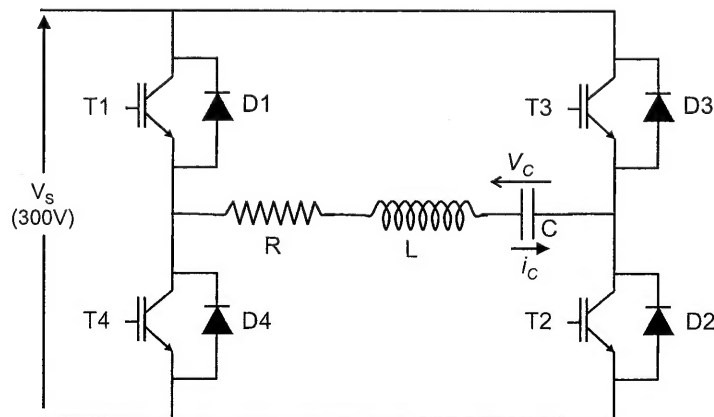


Figure Q4(b)

Continued...

Appendix A-1

MOTOROLA
SEMICONDUCTOR TECHNICAL DATA

 Order this document
 by MJ16018/D

Designer's™ Data Sheet
NPN Silicon Power Transistors
1.5 kV SWITCHMODE Series

These transistors are designed for high-voltage, high-speed, power switching in inductive circuits where fall time is critical. They are particularly suited for line-operated switchmode applications.

Typical Applications: Features:

- Switching Regulators
- Inverters
- Solenoids
- Relay Drivers
- Motor Controls
- Deflection Circuits
- Collector-Emitter Voltage — $V_{CEV} = 1500 \text{ Vdc}$
- Fast Turn-Off Times
 - 80 ns Inductive Fall Time — 100°C (Typ)
 - 110 ns Inductive Crossover Time — 100°C (Typ)
 - 4.5 μs Inductive Storage Time — 100°C (Typ)
- 100°C Performance Specified for:
 - Reverse-Biased SOA with Inductive Load
 - Switching Times with Inductive Loads
 - Saturation Voltages
 - Leakage Currents

MAXIMUM RATINGS

Rating	Symbol	MJ16018	MJW16018	Unit
Collector-Emitter Voltage	$V_{CEO(sus)}$	800		Vdc
Collector-Emitter Voltage	V_{CEV}	1500		Vdc
Emitter-Base Voltage	V_{EB}	6		Vdc
Collector Current — Continuous	I_C	10		Adc
— Peak(1)	I_{CM}	15		
Base Current — Continuous	I_B	8		Adc
— Peak(1)	I_{BM}	12		
Total Power Dissipation	P_D			
@ $T_C = 25^\circ\text{C}$		175	125	Watts
@ $T_C = 100^\circ\text{C}$		100	50	
Derate above $T_C = 25^\circ\text{C}$		1	1	W/ $^\circ\text{C}$
Operating and Storage Junction Temperature Range	T_J, T_{stg}	-65 to 200	-55 to 150	$^\circ\text{C}$

THERMAL CHARACTERISTICS

Characteristic	Symbol	Max	Unit
Thermal Resistance, Junction to Case	$R_{\theta JC}$	1	$^\circ\text{C/W}$
Lead Temperature for Soldering	T_L	275	$^\circ\text{C}$
Purposes: 1/8" from Case for 5 Seconds			

(1) Pulse Test: Pulse Width = 5 μs , Duty Cycle $\leq 10\%$.

Designer's Data for "Worst Case" Conditions — The Designer's Data Sheet permits the design of most circuits entirely from the information presented. SOA Limit curves — representing boundaries on device characteristics — are given to facilitate "worst case" design.

Preferred devices are Motorola recommended choices for future use and best overall value.

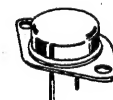
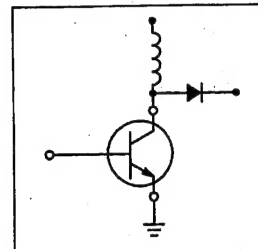
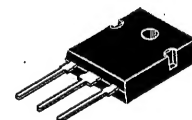
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REV 1

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MJ16018*
MJW16018*

*Motorola Preferred Device

POWER TRANSISTORS
10 AMPERES
800 VOLTS
125 AND 175 WATTS

 CASE 1-07
 TO-204AA
 MJ16018

 CASE 340F-03
 TO-247AE
 MJW16018

MOTOROLA

Continued...

Appendix A-2

MJ16018 MJW16018

ELECTRICAL CHARACTERISTICS ($T_C = 25^\circ\text{C}$ unless otherwise noted)

Characteristic	Symbol	Min	Typ	Max	Unit
OFF CHARACTERISTICS(1)					
Collector-Emitter Sustaining Voltage (Table 1) ($I_C = 50\text{ mA}$, $I_B = 0$)	$V_{CEO(sus)}$	800	—	—	Vdc
Collector Cutoff Current ($V_{CEV} = 1500\text{ Vdc}$, $V_{BE(off)} = 1.5\text{ Vdc}$) ($V_{CEV} = 1500\text{ Vdc}$, $V_{BE(off)} = 1.5\text{ Vdc}$, $T_C = 100^\circ\text{C}$)	I_{CEV}	—	—	0.25 1.5	mAdc
Collector Cutoff Current ($V_{CE} = 1500\text{ Vdc}$, $R_{BE} = 50\ \Omega$, $T_C = 100^\circ\text{C}$)	I_{CER}	—	—	2.5	mAdc
Emitter Cutoff Current ($V_{EB} = 6\text{ Vdc}$, $I_C = 0$)	I_{EBO}	—	—	0.1	mAdc
SECOND BREAKDOWN					
Second Breakdown Collector Current with Base Forward Biased	$I_{S/b}$	See Figure 13			
Clamped Inductive SOA with Base Reverse Biased	RBSOA	See Figure 14			
ON CHARACTERISTICS(1)					
Collector-Emitter Saturation Voltage ($I_C = 5\text{ Adc}$, $I_B = 2\text{ Adc}$) ($I_C = 10\text{ Adc}$, $I_B = 5\text{ Adc}$) ($I_C = 5\text{ Adc}$, $I_B = 2\text{ Adc}$, $T_C = 100^\circ\text{C}$)	$V_{CE(sat)}$	— — —	— — —	1 5 1.5	Vdc
Base-Emitter Saturation Voltage ($I_C = 5\text{ Adc}$, $I_B = 2\text{ Adc}$) ($I_C = 5\text{ Adc}$, $I_B = 2\text{ Adc}$, $T_C = 100^\circ\text{C}$)	$V_{BE(sat)}$	— —	— —	1.5 1.5	Vdc
DC Current Gain ($I_C = 5\text{ Adc}$, $V_{CE} = 5\text{ Vdc}$)	h_{FE}	4	—	—	—
DYNAMIC CHARACTERISTICS					
Output Capacitance ($V_{CB} = 10\text{ Vdc}$, $I_E = 0$, $f_{test} = 1\text{ kHz}$)	C_{ob}	—	—	450	pF

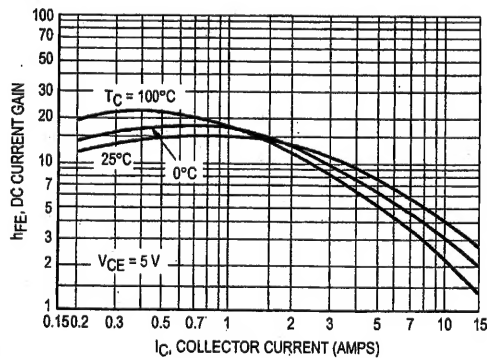
(1) Pulse Test: $PW = 300\ \mu\text{s}$, Duty Cycle $\leq 2\%$.

Figure 1. DC Current Gain

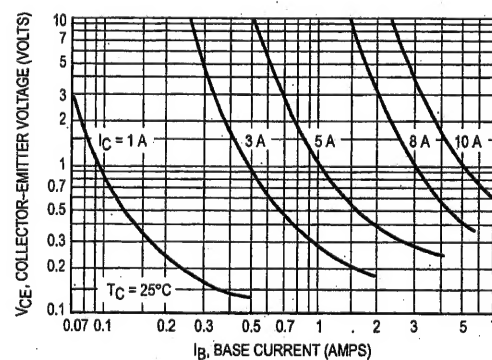


Figure 2. Collector Saturation Region

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Examination Formula Sheet (Rev 4.0)

AC-DC Converters

Single Phase Uncontrolled Rectifiers (Half wave), R load	Single Phase Uncontrolled Rectifiers (Half wave), RL Load
$V_{o,avg} = \frac{\sqrt{2}V_{s,rms}}{\pi}, V_{o,rms} = \frac{V_{s,rms}}{\sqrt{2}}$	$V_{o,avg} = \frac{\sqrt{2}V_{s,rms}}{2\pi} [1 - \cos(\beta)]$ $V_{o,rms} = \frac{V_{s,rms}}{\sqrt{2\pi}} \sqrt{\beta - \frac{\sin 2\beta}{2}} \quad \beta \approx \pi + \theta, \theta = \tan^{-1}\left(\frac{\omega L}{R}\right)$
Single Phase Uncontrolled Rectifiers (Bridge Full wave)	Three Phase Uncontrolled Rectifiers (Half wave)
$V_{o,avg} = \frac{2\sqrt{2}V_{s,rms}}{\pi}, V_{o,rms} = V_{s,rms}$	$V_{o,avg} = \frac{3\sqrt{3}V_{l-n}}{\sqrt{2\pi}}, V_{o,rms} = 1.19V_{l-n}$
Three Phase Uncontrolled Rectifiers (Full wave)	Single Phase controlled Rectifiers (Half wave)
$V_{o,avg} = \frac{3\sqrt{2}V_{l-l}}{\pi}, V_{o,rms} = 0.963 V_{l-l}$	$V_{o,avg} = \frac{V_{s,rms}}{\sqrt{2\pi}} (1 + \cos \alpha) \quad R$ Load $V_{o,avg} = \frac{V_{s,rms}}{\sqrt{2\pi}} (\cos \alpha + \cos \beta) \quad RL \text{ Load}$
Single Phase controlled Rectifiers (Bridge Full wave)	Three Phase controlled Rectifiers (Half wave)
$V_{o,avg} = \frac{\sqrt{2}V_{s,rms}}{\pi} (1 + \cos \alpha) \quad R$ Load $V_{o,avg} = \frac{2\sqrt{2}V}{\pi} \cos \alpha \quad RL$ Load	$V_{o,avg} = \frac{3\sqrt{2}}{2\pi} V_{AN} \left(1 + \cos\left(\frac{\pi}{6} + \alpha\right)\right)$
Three Phase controlled Rectifiers (Full wave)	
$V_{o,avg} = \frac{3\sqrt{6}}{\pi} V_{AN} \cos \alpha$	

DC-DC Converters

Buck Converter (CCM)	Buck Converter (DCM)
$V_o = DV_d$ $I_{L,max} = V_o \left[\frac{1}{R} + \frac{(1-D)}{2Lf_s} \right]$ $I_{L,min} = V_o \left[\frac{1}{R} - \frac{(1-D)}{2Lf_s} \right]$	$\frac{V_o}{V_d} = \frac{D}{D + \Delta_1}$ $I_o = \frac{V_d T_s}{2L} D \Delta_1$

Continued...

DC-DC Converters (cont.)

Boost Converter (CCM)	Boost Converter (DCM)
$V_o = \frac{V_d}{1-D}$ $I_{L\max} = \frac{V_d}{(1-D)^2 R} + \frac{V_d D T_s}{2L}$ $I_{L\min} = \frac{V_d}{(1-D)^2 R} - \frac{V_d D T_s}{2L}$	$\frac{V_o}{V_d} = \frac{\Delta_1 + D}{\Delta_1}$ $I_o = \frac{V_d T_s}{2L} D \Delta_1$
Buck-Boost Converter (CCM)	Buck-Boost Converter (DCM)
$V_o = \frac{V_d D}{1-D}$ $I_{L\max} = \frac{V_d D}{R(1-D)^2} + \frac{V_d D T_s}{2L}$ $I_{L\min} = \frac{V_d D}{R(1-D)^2} - \frac{V_d D T_s}{2L}$	$\frac{V_o}{V_d} = \frac{D}{\Delta_1}$ $I_o = \frac{V_d D}{2f_s L} (D + \Delta_1) - \frac{D I_o}{\Delta_1}$
Flyback Converter (CCM)	Flyback Converter (DCM)
$\frac{V_o}{V_d} = \frac{N_2}{N_1} \frac{D}{1-D}$ $I_{L\max} = \frac{V_d D}{R(1-D)^2} \left[\frac{N_2}{N_1} \right]^2 + \frac{V_d D T_s}{2L_m}$ $I_{L\min} = \frac{V_d D}{R(1-D)^2} \left[\frac{N_2}{N_1} \right]^2 - \frac{V_d D T_s}{2L_m}$	$\frac{V_o}{V_d} = D \sqrt{\frac{R}{2f_s L_m}}$ $I_o = \frac{V_o}{R}$

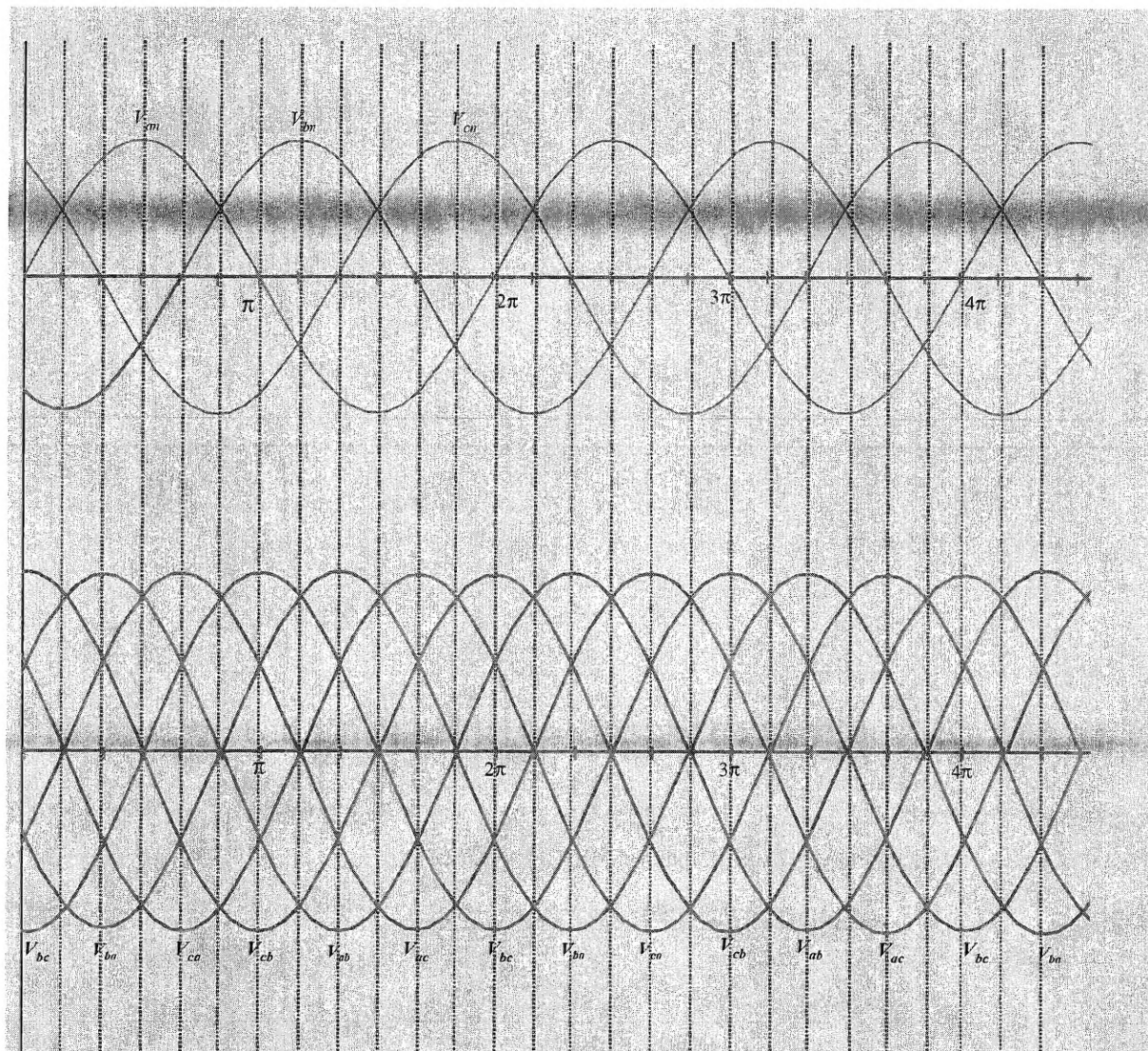
DC- AC Converters

<p>Single-Phase Half-bridge Inverter with RL load</p> $v_o(\omega t) = \sum_{n=1,3,5,\dots}^{\infty} \frac{2V_s}{n\pi} \sin(n\omega t)$ <p>Single-phase full-bridge PWM inverter (Square Wave)</p> $v_o(\omega t) = \sum_{n=1,3,5,\dots}^{\infty} \frac{4V_s}{n\pi} \sin(n\omega t)$ <p>Single-phase full-bridge PWM inverter (Quasi Square Wave)</p> $v(\omega t) = \sum_{n=1,3,5,\dots}^{\infty} \frac{4V_s}{n\pi} \sin \frac{nD\pi}{2} \cos n(\omega t - \frac{D\pi}{2})$	<p>Resonant Converters</p> $\omega_r = \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}$ $i(t) = \frac{V_s + V_c}{\omega_r L} e^{-\alpha t} \sin \omega_r t, \quad \alpha = \frac{R}{2L}$ $V_c = V_s \left(\frac{e^{2z} - 1}{e^{2z} + 1} \right), \quad z = \frac{\alpha \pi}{\omega_r}$ $V_{cp} = V_s \left(1 + \frac{2e^{2z}}{e^{2z} + 1} \right)$
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Appendix (For Question 2(c))- Please attach to the answer booklet

Student ID : Table No.:.....



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